

iC-PR Series

REFLECTIVE OPTO ENCODERS



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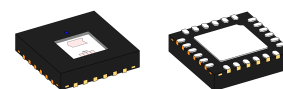
FEATURES

- ◆ Lensless, reflective opto-encoder iCs, compact, high-resolution, incremental
- ◆ Suitable reflective code discs of $\varnothing 4$, $\varnothing 14$, $\varnothing 26$ and $\varnothing 43$ mm and linear scales with $256 \mu\text{m}$ period length
- ◆ Monolithic *HD Phased Array* with excellent signal matching
- ◆ Integrated blue LED with power control, *EncoderBlue*®
- ◆ Low-noise signal amplifiers with high EMI tolerance
- ◆ Pin-selectable modes of operation:
Digital A/B/Z (x1, x2, x4, x8, x16 interpolated), analog COS/SIN with analog or digital Z
- ◆ Pin-selectable index gating:
Ungated (1 T), B-gated (0.5 T), AB-gated (0.25 T)
- ◆ Pin-selectable minimal edge distance: 80 ns, 1 μs , 10 μs
- ◆ Complementary quadrature outputs PA, NA, PB and NB
- ◆ Complementary index outputs PZ and NZ
- ◆ Analog signal output for ease of alignment and resolution enhancement by external interpolation
- ◆ Operating temperature range of -40°C to $+105^\circ\text{C}$
- ◆ Compact and lensless optoQFN mold package
- ◆ Evaluation kits on request

APPLICATIONS

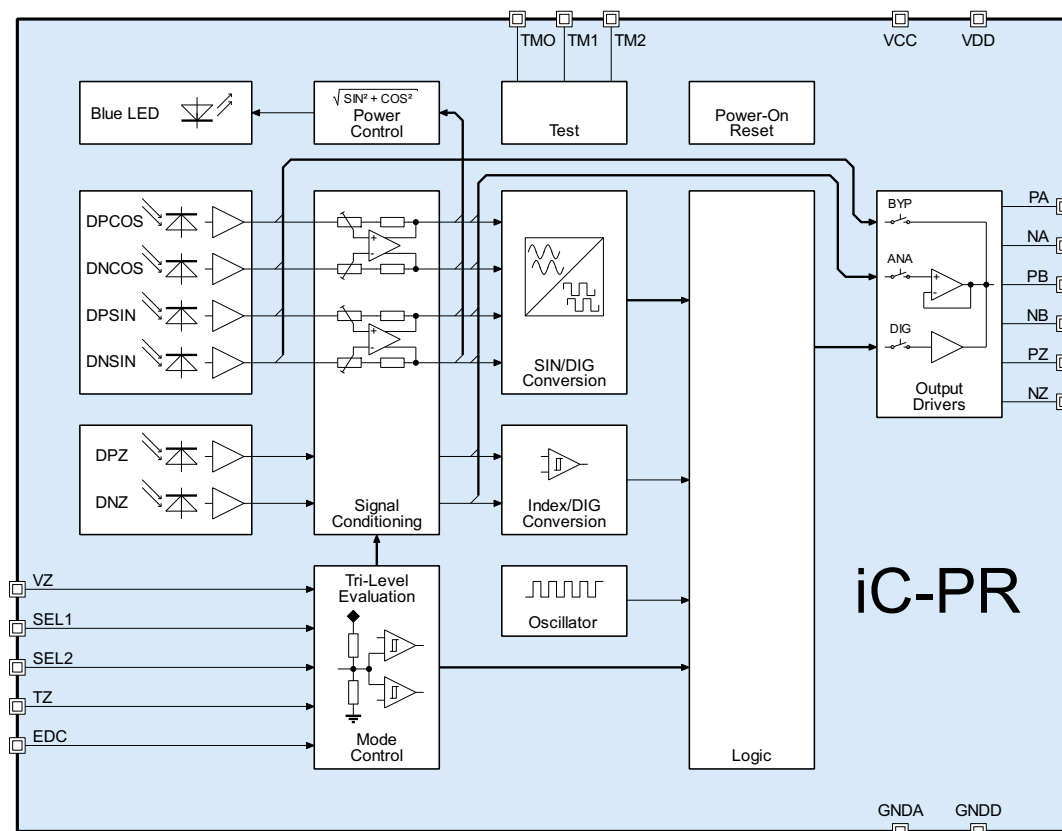
- ◆ Incremental encoders
- ◆ Miniature motors and actuators
- ◆ X-Y and linear stages
- ◆ Factory automation robots
- ◆ Consumer robots

PACKAGES



optoQFN24-4x4
4 mm x 4 mm x 0.9 mm
RoHS compliant

BLOCK DIAGRAM



DESCRIPTION

The iC-PR series are advanced optical, reflective, lensless encoder iCs featuring integrated HD Phased Array photosensors and a blue LED. They provide high signal quality with relaxed alignment tolerances. Differential digital ABZ outputs with or without interpolation or analog SIN/COS outputs with index are available. Typical applications are incremental encoders for motor control.

Blue-enhanced photosensors are adapted to the short wavelength of the embedded blue LED, and provide low-jitter outputs due to improved signal contrast. The unique assembly technology of the blue LED emitter and sensors results in low optical crosstalk.

Low-noise transimpedance amplifiers, arranged in a paired layout to ensure excellent channel matching, are used to convert the sensor signals into voltages of several hundred millivolts.

Various operation modes are selectable via tri-level inputs SEL1 and SEL2: Digital outputs with native (x1) or interpolated resolution (x2, x4, x8 or x16), analog outputs or mixed analog/digital outputs, where the latter one combines analog COS/SIN signals with a digital index. The amplified analog output signals allow for inspection and monitoring of encoder assembly. Moreover, feeding external interpolation circuits (e.g. iC-NQ, iC-TW8 or iC-TW28) is possible.

Index gating is also pin-selectable via input TZ: The options are ungated (1 T), B-gated (0.5 T) or AB-gated (0.25 T).

Via tri-level input EDC a minimal edge distance of 80 ns, 1 μ s or 10 μ s can be preset for digital operation modes.

The devices feature a low power consumption. They run at single-sided analog supplies of 4.5 V up to 5.5 V and single-sided digital supplies of 3.0 V up to 5.5 V.

iC-PR4307

Code disc \varnothing : 43.0 mm
Native CPR: 720

iC-PR26xx

Code disc \varnothing : 26.0 mm
Native CPR: 250, 256, 360

iC-PR1456

Code disc \varnothing : 14.0 mm
Native CPR: 250, 256

iC-PR0464

Code disc \varnothing : 4.0 mm
Native CPR: 64

iC-PR256

Linear scale: 256 μ m period length

General notice on materials under excessive conditions

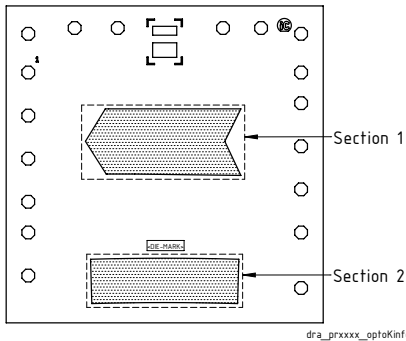
Epoxy resins (such as solder resists, IC package and injection molding materials, as well as adhesives) may show discoloration, yellowing, and surface changes in general when exposed longterm to high temperatures, humidity, irradiation, or due to thermal treatments for soldering and other manufacturing processes.

Equally, standard molding materials used for IC packages can show visible changes induced by irradiation, among others when exposed to light of shorter wavelengths, blue light for instance. Such surface effects caused by visible or IR LED light are rated to be of cosmetic nature, without influence to the chip's function, its specifications and reliability.

Note that any other material used in the system (e.g. varnish, glue, code disc) should also be verified for irradiation effects.

PACKAGING INFORMATION

SENSOR LAYOUT



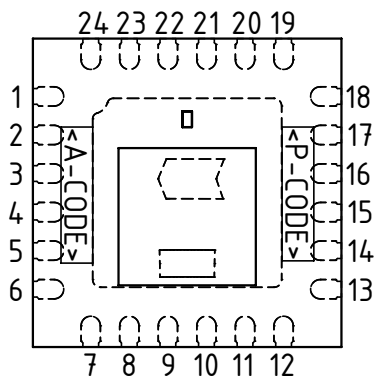
AOI CRITERIA

| <Die Mark> | <Section> | <Area Class> ¹ |
|------------|-----------|---------------------------|
| iC PRnnnn | 1 | A25 |
| | 2 | A40 |

¹ Inspection class for the optical inspection of detector areas. Refer to [Optical Selection Criteria](#) for further description.

PIN CONFIGURATION

oQFN24-4x4 (4 mm x 4 mm)



PIN FUNCTIONS

No. Name Function

| | | |
|----|------|--|
| 1 | VDD | +3.0 V...+5.5 V Digital Supply Voltage |
| 2 | SEL1 | Mode Selection Input 1 |
| 3 | SEL2 | Mode Selection Input 2 |
| 4 | TZ | Index Gating Control Input |
| 5 | PZ | Index Output Z+ |
| 6 | NZ | Index Output Z- |
| 13 | EDC | Edge Distance Control Input |
| 14 | NB | Incr. Output B- / Analog SIN- |
| 15 | PB | Incr. Output B+ / Analog SIN+ |
| 16 | NA | Incr. Output A- / Analog COS- |
| 17 | PA | Incr. Output A+ / Analog COS+ |
| 18 | GNDD | Digital Ground |
| 19 | GNDA | Analog Ground |
| 20 | TMO | Test Mode Output ²⁾ |
| 21 | TM2 | Test Mode Input 2 ²⁾ |
| 22 | TM1 | Test Mode Input 1 ²⁾ |
| 23 | VZ | Index Detection Control Input |
| 24 | VCC | +4.5 V...+5.5 V Analog Supply Voltage |

7..12 n.c.¹⁾

BP Backside Paddle ³⁾

IC top marking: <P-CODE> = product code, <A-CODE> = assembly code (subject to changes);

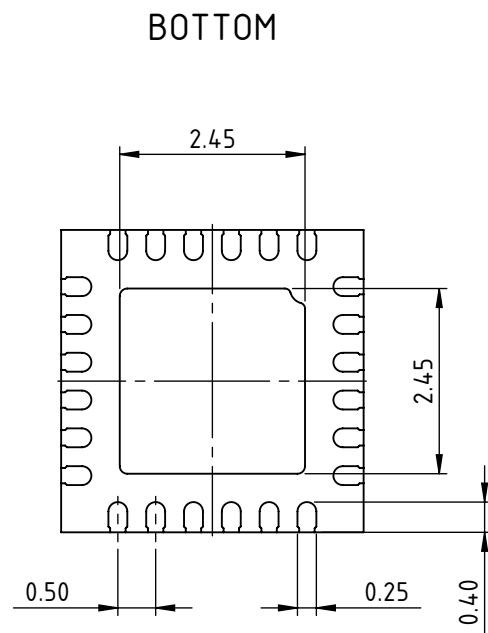
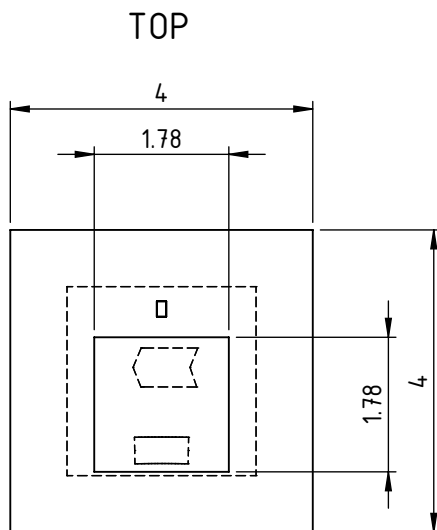
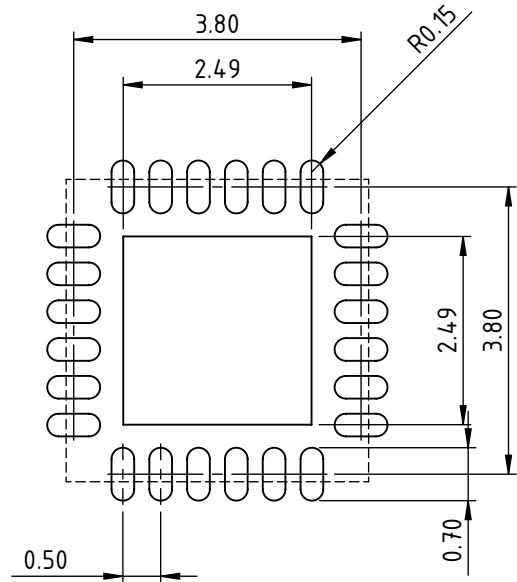
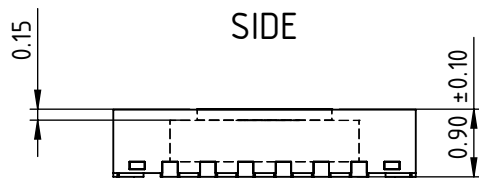
1) Pin numbers marked with n.c. are not connected.

2) The test pins may remain unconnected. TM1, TM2, and TMO can be tied to GNDA to increase the noise immunity.

3) The backside paddle has to be connected by a single link to GNDA. A current flow across the paddle is not permissible.

PACKAGE DIMENSIONS

RECOMMENDED PCB-FOOTPRINT



All dimensions given in mm. Tolerances of form and position according to JEDEC MO-220.
 Positional tolerance of sensor pattern: $\pm 70\mu\text{m}$ / $\pm 1^\circ$ (with respect to center of backside pad).
 Maximum molding excess $+20\mu\text{m}$ / $-75\mu\text{m}$ versus surface of glass/reticle.

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ABSOLUTE MAXIMUM RATINGS

These ratings do not imply operating conditions; functional operation is not guaranteed. Beyond these ratings device damage may occur.

| Item No. | Symbol | Parameter | Conditions | | | Unit |
|----------|--------|---------------------------------|---------------------------------------|------|------|------|
| | | | | Min. | Max. | |
| G001 | VCC | Voltage at VCC | | -0.3 | 6 | V |
| G002 | I(VCC) | Current in VCC | | -20 | 100 | mA |
| G003 | VDD | Voltage at VDD | | -0.3 | 6 | V |
| G004 | I(VDD) | Current in VDD | | -20 | 100 | mA |
| G005 | I() | Pin Current, all signal outputs | | -20 | 20 | mA |
| G006 | Vd() | Electrostatic Discharge | HBM, 100 pF discharged through 1.5 kΩ | | 2 | kV |
| G007 | Tj | Junction Temperature | | -40 | 150 | °C |
| G008 | Ts | Chip Storage Temperature | | -40 | 150 | °C |

¹ JEDEC document JEP 155: 500V HBM allows safe manufacturing with a standard ESD control process

THERMAL DATA

Operating conditions: VCC = 4.5...5.5 V, VDD = 3.0...5.5 V

| Item No. | Symbol | Parameter | Conditions | | | | Unit |
|----------|--------|---------------------------------------|--|------|------|------|------|
| | | | | Min. | Typ. | Max. | |
| T01 | Ta | Operating Ambient Temperature Range | | -40 | | 105 | °C |
| T02 | Ts | Permissible Storage Temperature Range | | -40 | | 105 | °C |
| T03 | Tpk | Soldering Peak Temperature | tpk < 20 s, convection reflow MSL 3 (max. floor life 168 h at 30 °C and 60 % RH); Refer to Handling and Soldering Conditions for details. | | | 245 | °C |
| T04 | Rthja | Thermal Resistance Chip to Ambient | package mounted on PCB according to JEDEC standard | | 50 | | K/W |

All voltages are referenced to ground unless otherwise stated.

All currents flowing into the device pins are positive; all currents flowing out of the device pins are negative.

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ELECTRICAL CHARACTERISTICS

Operating conditions: VCC = 4.5...5.5 V, VDD = 3.0...5.5 V, Tj = -40...105 °C, unless otherwise noted

| Item No. | Symbol | Parameter | Conditions | | | | Unit |
|---|-----------|--|---|----------------------------------|---------------------|----------------------|---------------------------------|
| | | | | Min. | Typ. | Max. | |
| Total Device | | | | | | | |
| 001 | VCC | Permissible Analog Supply Voltage | | 4.5 | | 5.5 | V |
| 003 | VDD | Permissible Digital Supply Voltage | $VDD \leq VCC$ | 3.0 | | 5.5 | V |
| 004 | I() | Supply Current | $I(VCC)+I(VDD)$, Photocurrent Amplifiers within op. range, $f_{out}() < 250$ kHz, no load refer to Table 5 for details | | 20 | | mA |
| Photocurrent Amplifiers | | | | | | | |
| 101 | Z() | Equivalent Transimpedance Gain | $Z() = V_{out}()/I_{ph}()$, Tj = 27 °C for PA, NA, PB, NB for PZ, NZ | | 4 6 | | MΩ MΩ |
| 102 | fc()hi | Cut-off Frequency (-3 dB) | | 200 | | | kHz |
| Analog Outputs PA, NA, PB, NB, PZ, NZ | | | | | | | |
| 201 | Vout()ac | AC Signal Amplitude | Mode AAMP Mode A250 Mode A500DZ | | 250 250 500 | | mV mV mV |
| 204 | Vout()mx | Permissible Maximum Output Voltage | Mode AAMP refer to Table 5 for typical values | | | 2.2 | V |
| 206 | Vout()d | Dark Signal Level | Mode AAMP voltage at NZ voltage at PA, NA, PB, NB with no illumination T = -40 °C T = 25 °C T = 125 °C | 870 780 640 | 980 880 765 | 1140 1060 940 | mV mV mV |
| 207 | ΔVout()d | Dark Signal Matching of A, B | Mode AAMP, output vs. output | -2.5 | | 2.5 | mV |
| 208 | TCVout()d | Temperature Coefficient of Dark Signal Level | Mode AAMP voltage at NZ voltage at PA, NA, PB, NB with no illumination | | -1.4 | | mV/K |
| 209 | VREF | Reference Voltage | Mode A250, A500DZ | 48 | 50 | 52 | %VCC |
| 210 | V()act | Signal Level at PZ-activation | $V(PZ)_{act} = V(NZ) - V(PZ)$ at activation see also Figure 1 refer to Table 5 for details | | 180 ..290 | | mV mV |
| 211 | I()mx | Permissible Load Current | Mode A250, A500DZ Mode AAMP | -1000 -100 | | 1000 10 | μA μA |
| 212 | C()mx | Permissible Capacitive Load | | | | 20 | pF |
| Digital Outputs PA, NA, PB, NB, PZ, NZ | | | | | | | |
| 401 | fout() | Maximum Frequency per Output | Mode DX1, EDC low Mode DX2, EDC low Mode DX4, EDC low Mode DX8, EDC low Mode DX16, EDC low | 0.2 0.4 0.8 1.6 1.85 | | | MHz MHz MHz MHz MHz |
| 402 | AArel | AB Duty Cycle Variation | Mode DX1 Modes DX2, DX4, DX8, DX16 see also Figure 2 | -5 -10 | | 5 10 | % % |
| 403 | HysD | Digital Hysteresis of Interpolator | Hysteresis with respect to one cycle of sine/cosine | | 5.6 | | ° |
| 404 | Vs()lo | Saturation Voltage low | I() = 4 mA see also Figure 3 | | | 0.4 | V |
| 405 | Isc()lo | Short-Circuit Current low | V() = VDD | 7 | | 110 | mA |
| 406 | Vs()hi | Saturation Voltage high | $Vs(hi) = VDD - V()$, I() = -4 mA see also Figure 3 | | | 0.4 | V |
| 407 | Isc()hi | Short-Circuit Current high | V() = 0 V | -110 | | -7 | mA |
| 408 | Tedc() | Edge Distance Control Time | EDC low EDC high EDC open | 45 6600 640 | 80 10000 1000 | 135 14900 1520 | ns ns ns |

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ELECTRICAL CHARACTERISTICS

Operating conditions: VCC = 4.5...5.5 V, VDD = 3.0...5.5 V, Tj = -40...105 °C, unless otherwise noted

| Item No. | Symbol | Parameter | Conditions | | | | Unit |
|---|---------|---|--|------|-------|------|------|
| | | | | Min. | Typ. | Max. | |
| Tri-Level Programming Inputs SEL1, SEL2, EDC, TZ, VZ | | | | | | | |
| 601 | Vt()lo | Tri-Level Threshold Voltage low | | 10 | | | %VCC |
| 602 | Vt()hi | Tri-Level Threshold Voltage high | | | | 90 | %VCC |
| 603 | Vt()mid | Tri-Level Threshold Voltage mid | | 30 | | 70 | %VCC |
| 604 | V0() | Pin-Open Voltage | | 45 | 50 | 55 | %VCC |
| 605 | Rpd() | Pull-Down Resistor | V() = VCC | 65 | | 140 | kΩ |
| 606 | Rpu() | Pull-Up Resistor | V() = GNDA | 65 | | 140 | kΩ |
| LED Power Control | | | | | | | |
| 901 | Iop() | Permissible LED Current | | 0.5 | | 20 | mA |
| 902 | Ictrl() | Controlled LED Output Current | refer to Table 5 for details | | 5..10 | | mA |
| Power-On Reset | | | | | | | |
| A01 | VCCcon | Turn-on Threshold VCC (power-on release) | increasing voltage at VCC VDD > VDDon, LED Current and Photocurrent Amplifiers within op. range | | | 3.95 | V |
| A02 | VCCoff | Turn-off Threshold VCC (power-down reset) | decreasing voltage at VCC VDD > VDDon, LED Current and Photocurrent Amplifiers within op. range | 3.00 | | | V |
| A03 | VCChys | Threshold Hysteresis VCC | VCChys = VCCcon - VCCoff | 200 | 300 | 400 | mV |
| A04 | VDDon | Turn-on Threshold VDD (power-on release) | increasing voltage at VDD VCC > VCCcon, LED Current and Photocurrent Amplifiers within op. range | | | 2.95 | V |
| A05 | VDDoff | Turn-off Threshold VDD (power-down reset) | decreasing voltage at VDD VCC > VCCcon, LED Current and Photocurrent Amplifiers within op. range | 2.3 | | | V |
| A06 | VDDhys | Threshold Hysteresis VDD | VDDhys = VDDon - VDDoff | 180 | 240 | 300 | mV |

ELECTRICAL CHARACTERISTICS: Diagrams

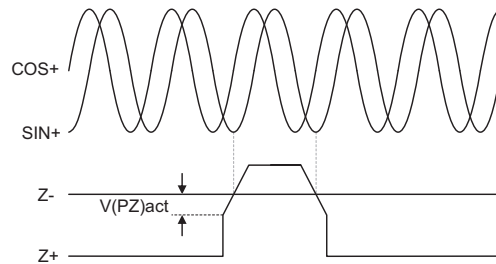


Figure 1: Z-signal level definition.

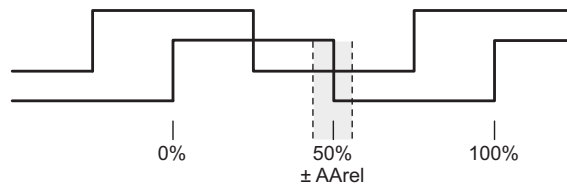


Figure 2: Definition of AB duty cycle variation.

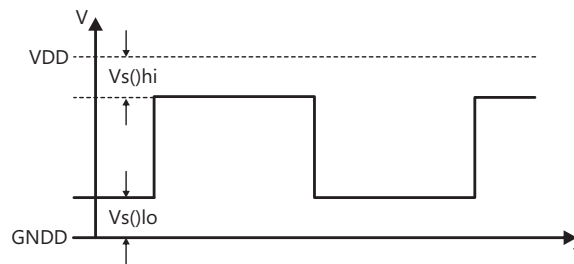


Figure 3: Digital Signal Levels.

SIGNAL DEFINITIONS

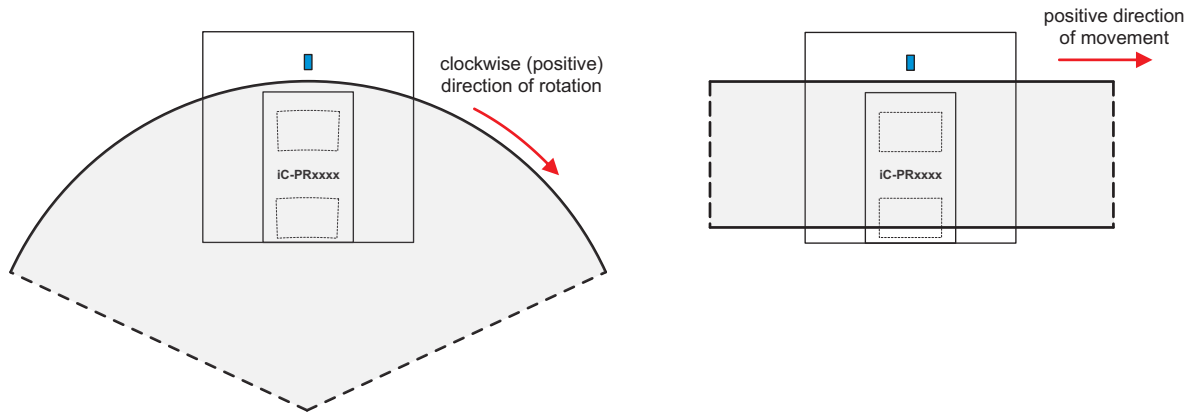


Figure 4: Definition of clockwise rotation / positive direction of movement.

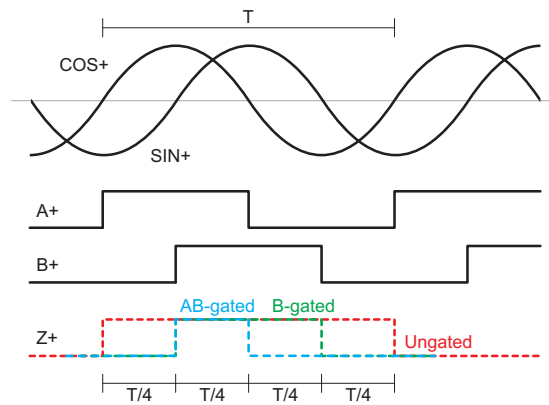


Figure 5: Signal definitions for clockwise rotation / positive direction of movement.

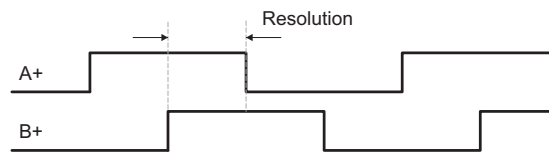


Figure 6: Definition of resolution for linear series.

VOLTAGE DOMAINS

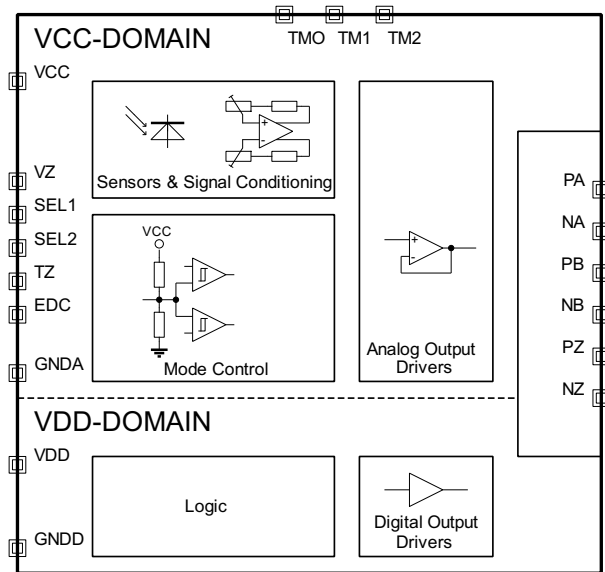


Figure 7: Analog and digital voltage domains

In iC-PR, the analog and the digital supply voltages are applied at different pins. On the one hand, this improves the quality of the analog signals, on the other hand, the digital signal output levels can be chosen to match subsequent circuitry. The internal voltage domains are shown in Fig. 7.

Please note:

- Permissible voltage ranges for VCC, VDD specified in Electrical Characteristics, parameters No. 001 and No. 003, respectively
- $VDD \leq VCC$
- reference voltage / high level for mode pins is VCC
- GNDA and GNDD must be at the same potential but should be connected with separate lines from a star point on the PCB

OPERATION MODES

The iC-PR series features 8 principle operation modes, which are selectable by the voltages applied to the pins SEL1 and SEL2, as summarized in Table 1.

These tri-level inputs might be connected to a voltage below $V_t()_{lo}$ (low, see 601), a voltage above $V_t()_{hi}$ (high, see 602) or a voltage between the specified values of $V_t()_{mid}$ (open, see 603). For other voltages the function is undefined.

The open configuration can be easily obtained by an external voltage divider. Alternatively, when the pin is left unconnected, the iC itself biases the input at 50% VCC (see 604).

Note: Static pin voltages at SEL1 and SEL2 are required during operation. If changing the setting of SEL1 and SEL2 pins during operation, power-on reset of iC-PR is required.

| SEL1 | SEL2 | Mode | Description |
|------|------|--------|--|
| low | high | DX1 | digital A/B/Z (x1 interpolation) |
| high | low | DX2 | digital A/B/Z (x2 interpolation) |
| low | open | DX4 | digital A/B/Z (x4 interpolation) |
| high | high | DX8 | digital A/B/Z (x8 interpolation) |
| high | open | DX16 | digital A/B/Z (x16 interpolation) |
| open | low | A250 | analog COS/SIN ($V_{REF} \pm 250$ mV), analog Z, see Figure 8 |
| open | high | AAMP | analog COS/SIN (transimpedance amps. ± 250 mV), analog Z, see Figure 8 |
| open | open | A500DZ | analog COS/SIN ($V_{REF} \pm 500$ mV), digital Z (ungated), see Figure 8 |

Table 1: Operation modes selectable by pins SEL1/2.

ANALOG / MIXED OPERATION MODES

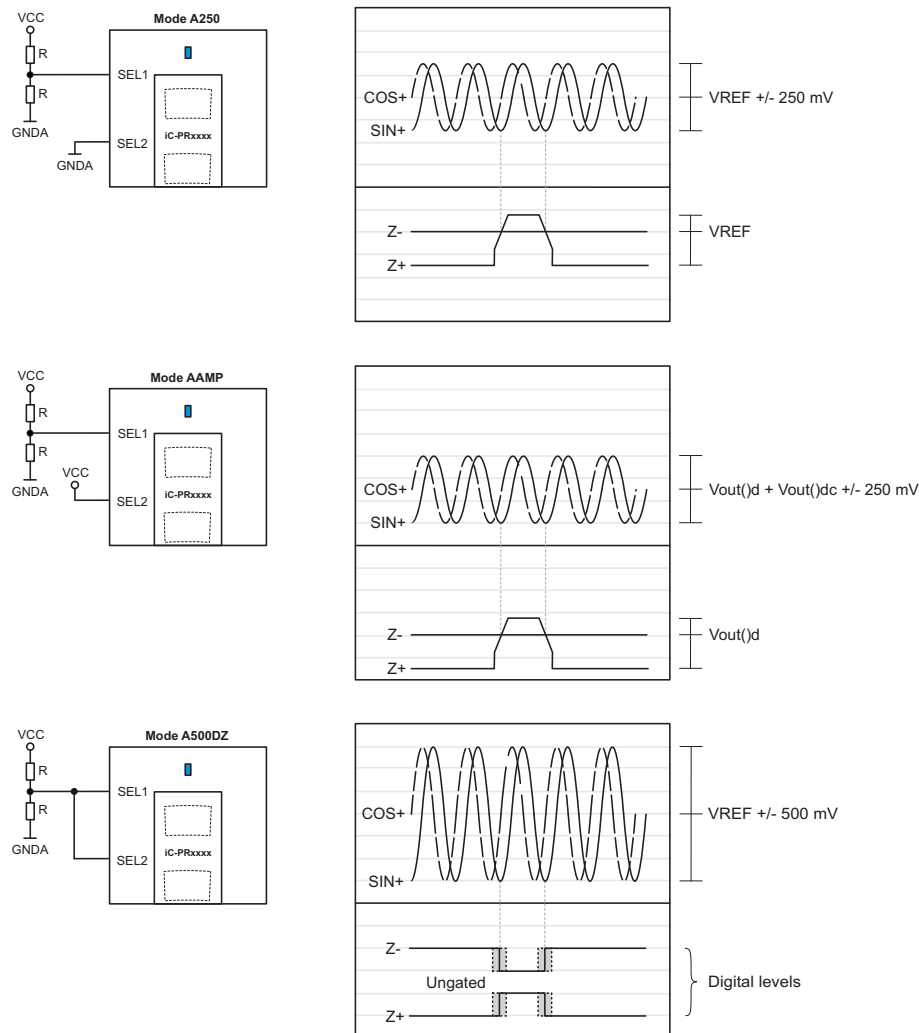


Figure 8: Analog / mixed operation modes. Complementary signals COS- and SIN- not shown.

- $V_{out}()d$ is the dark signal level of the analog signals. It is independent of illumination but proportional to temperature.
- $V_{out}()dc$ is the dc-level of the analog signals with respect to the dark signal level. It is proportional to illumination but independent of temperature.
- The permissible load current for the analog outputs is specified as parameter 211 in the Electrical Characteristics.
- For correct functionality of the Z-index, programming pin VZ has to be set to a proper value as described in section INDEX DETECTION THRESHOLD.

DIGITAL OPERATION MODES

INTERPOLATION FACTOR AND INDEX GATING

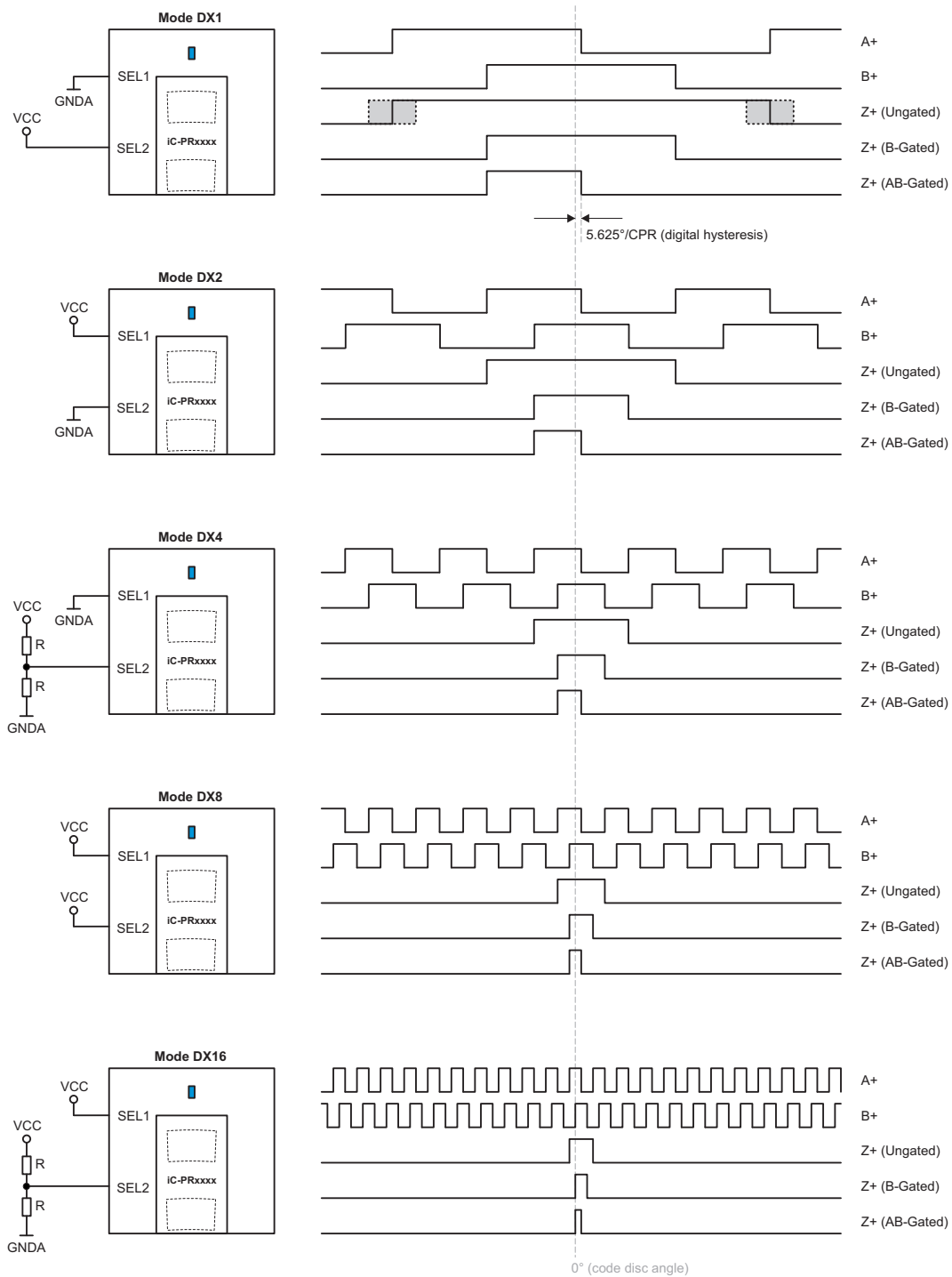


Figure 9: Digital operation modes (interpolation and index gating). Complementary signals A-, B- and Z- not shown.

An overview of the digital modes (interpolation and index gating) is depicted in Figure 9. The index gating can be controlled via tri-level pin TZ, as defined by Table 2.

Note: Static pin voltage at TZ is required during operation.

| TZ | Description |
|------|----------------------|
| low | B-gated index (180°) |
| high | Ungated index (360°) |
| open | AB-gated index (90°) |

Table 2: Index gating controlled by pin TZ.

For correct functionality of the Z-index, programming pin VZ has to be set to a proper value as described in section INDEX DETECTION THRESHOLD.

DIGITAL HYSTERESIS

In all interpolation modes the iC-PR series features a digital angular hysteresis of $\frac{360^\circ}{64 \cdot \text{CPR}}$, i.e. 1 LSB of the angular resolution in mode DX16. As illustrated in Figure 10, the digital hysteresis corresponds to a slip existing between the two rotating directions. In this way multiple switching of the incremental signals at the reversing point of a changing direction of rotation is prevented.

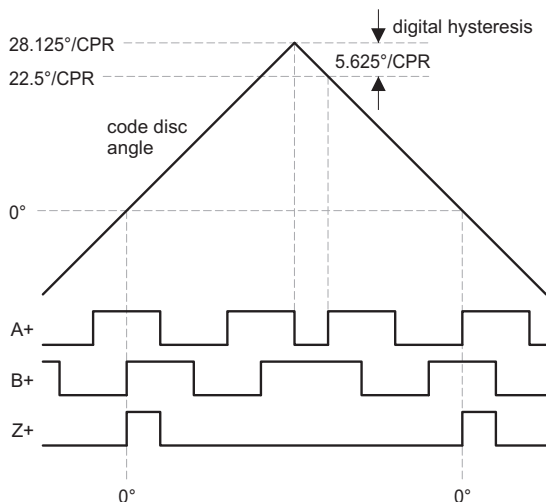


Figure 10: Digital hysteresis in mode DX16 with AB-gated index.

EDGE DISTANCE CONTROL

The edge distance is defined as the time between two consecutive AB edges, as depicted in Figure 11.

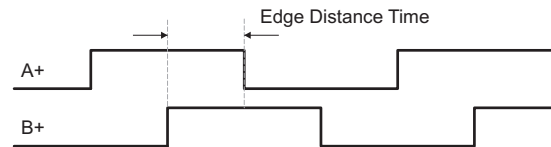


Figure 11: Definition of the edge distance time.

With the tri-level input pin EDC a minimal edge distance of 80 ns, 1 μs or 10 μs (typical values) can be configured to suit the system on hand (cable length, external counter). It is recommended to set EDC low.

Note: Static pin voltage at EDC is required during operation.

| EDC | Description |
|------|-----------------------------|
| low | 80 ns minimal edge distance |
| high | 10 μs minimal edge distance |
| open | 1 μs minimal edge distance |

Table 3: Minimal edge distance controlled by pin EDC.

STARTUP BEHAVIOR

When iC-PR is powered on, the digital outputs are held in a defined state:

$$\begin{aligned} PA = NA = PB = NB &= \text{low} \\ PZ = NZ &= \text{high} \end{aligned}$$

This specific combination of output signal levels is invalid during normal operation, hence signaling that the iC is in the startup phase. Once the logic has found and verified the code disc position, valid A/B/Z signals are then output henceforth.

Note: iC-PR will also enter or remain in the startup state, when the regulated LED current exceeds a specific value, e.g. due to code disc misalignment. Once the LED current returns to a valid range, the logic will again search for the code disc position and output valid A/B/Z signals afterwards.

INDEX DETECTION THRESHOLD

Via tri-level pin VZ an internal threshold for the index detection can be controlled, as described in Table 4. Setting VZ low (maximal threshold), a safe detection of the index pulse requires stronger illumination of the respective photodiodes, which also results in a stronger interference resistance against extraneous or stray light. On the other hand, with VZ high (minimal threshold) less illumination of the index photodiodes is required for a safe detection. However, in this case the interference resistance is reduced respectively. With VZ open the threshold lies in between the other two options.

For air gap above 1.5 mm (iC to code disc), the recommended value for VZ is shown in Table 5. For smaller

air gaps, it may be necessary to decrease the index detection threshold.

Note: VZ affects all operation modes, no matter if the index signal is analog or digital.

| VZ | Description |
|------|-------------------|
| low | Maximal threshold |
| high | Minimal threshold |
| open | Medium threshold |

Table 4: Index detection controlled by pin VZ.

POWER CONTROL

iC-PR devices regulate the current through the integrated blue LED, keeping the optical power constant regardless of aging effects, varying temperature or changes in air gap (iC to code disc).

In case of strong code disc misalignment or in the absence of any code disc, a maximum current is sent

through the LED, which corresponds to an overall supply current of typ. 80 mA.

When code disc and iC-PR are properly aligned, the LED current is significantly reduced and mainly depends on the code disc type and the actual air gap (see Table 5 for typ. supply current values).

SAFETY ADVICE

Depending on the mode of operation, these devices emit highly concentrated visible blue light which can be hazardous to the human eye.

Products which incorporate these devices have to follow the safety precautions given in IEC 60825-1 and IEC 62471.

HANDLING ADVICE

Because of the specific housing materials and geometries used, these LED devices are sensitive to rough handling or assembly and can thus be easily damaged

or may fail in regard to their electro-optical operation. Excessive mechanical stress or load on the LED surface or to the glass windows must be avoided.

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DEVICE OVERVIEW

| Device | CPR native | Code Disc | | Supply Current / mA | | Max. RPM | | VZ ≥1.5 mm ¹ | V(PZ)act /mV | Vout()mx /V |
|--------|---------------|-----------|------|---------------------|--------------------|-----------|------|----------------------------|-----------------|----------------|
| | | P/O Code | Type | 1.5mm ¹ | 2.0mm ¹ | DX1..8/Ax | DX16 | | | |

∅ 43 Series

| | | | | | | | | | | |
|-----------|-----|-------|---|----|----|--------|-------|-----|-----|------|
| iC-PR4307 | 720 | PR28S | P | 21 | 27 | 16 000 | 9 000 | low | 290 | 1.70 |
|-----------|-----|-------|---|----|----|--------|-------|-----|-----|------|

∅ 26 Series

| | | | | | | | | | | |
|-----------|-----|-------|---|----|----|--------|--------|------|-----|------|
| iC-PR2604 | 360 | PR24S | P | 21 | 26 | 32 000 | 18 000 | low | 290 | 1.55 |
| iC-PR2656 | 256 | PR25S | P | 16 | 18 | 45 000 | 25 000 | open | 280 | 1.55 |
| iC-PR2656 | 250 | PR30S | P | 16 | 18 | 45 000 | 25 000 | open | 280 | 1.55 |

∅ 14 Series

| | | | | | | | | | | |
|-----------|-----|-------|---|----|----|--------|--------|------|-----|------|
| iC-PR1456 | 256 | PR27S | P | 21 | 27 | 45 000 | 25 000 | high | 180 | 1.80 |
| iC-PR1456 | 250 | PR29S | P | 21 | 27 | 45 000 | 25 000 | high | 180 | 1.80 |

∅ 04 Series

| | | | | | | | | | | |
|-----------|----|-------|---|----|----|---------|---------|------|-----|------|
| iC-PR0464 | 64 | PR06S | M | 21 | 27 | 180 000 | 100 000 | high | 200 | 1.65 |
|-----------|----|-------|---|----|----|---------|---------|------|-----|------|

| Device | Res. DX16 | Code Disc | | Supply Current / mA | | Max. Speed / m/s | | VZ ≥1.5 mm ¹ | V(PZ)act mV | Vout()mx V |
|--------|--------------|-----------|------|---------------------|---------------------|------------------|------|----------------------------|----------------|---------------|
| | | P/O Code | Type | 1.5 mm ¹ | 2.0 mm ¹ | DX1..8/Ax | DX16 | | | |

Linear Series

| | | | | | | | | | | |
|----------|------|-------|---|----|----|----|----|-----|-----|------|
| iC-PR256 | 4 μm | PR01L | F | 16 | 18 | 50 | 28 | low | 290 | 1.55 |
|----------|------|-------|---|----|----|----|----|-----|-----|------|

Type M = Metal
 Type P = Polycarbonate
 Type F = Film
 Type [] = Glass

Definition of resolution for linear series see Figure 6.

Device availability on request.

Table 5: Device overview

¹ Air gap (iC vs. code disc)

DESIGN REVIEW: Notes On Chip Functions

| PRnnnn | | |
|----------------|--------------------------|--|
| Chip release Y | | |
| No. | Function, Parameter/Code | Description and Application Hints |
| | | No fiducials to align IC to reference structures on PCB. |

Table 6: Design review

| PRnnnn | | |
|-----------------------|--------------------------|-----------------------------------|
| Chip release X, X1, W | | |
| No. | Function, Parameter/Code | Description and Application Hints |
| | | None at time of printing. |

Table 7: Design review

APPLICATION NOTES

Application notes for iC-PR-series devices are shown separately.

iC-PR Series

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REVISION HISTORY

| Rel. | Rel. Date ¹ | Chapter | Modification | Page |
|------|------------------------|---------|-----------------|------|
| A1 | 2015-11-23 | | Initial Release | all |

| Rel. | Rel. Date ¹ | Chapter | Modification | Page |
|------|------------------------|----------------------------|--|------|
| A2 | 2016-03-31 | BLOCK DIAGRAM | Block diagram updated. | 1 |
| | | ELECTRICAL CHARACTERISTICS | 204, 212: Moved value from "min." to "max." as defined as "permissible" | 6 |
| | | SIGNAL DEFINITIONS | Figure for definition of resolution in linear series added. | 9 |
| | | OPERATION MODES | Description of analog modes in Table 1 updated. | 9 |
| | | DIGITAL OPERATION MODES | Recommended EDC configuration added. | 12 |
| | | INDEX DETECTION THRESHOLD | Updated description. | 13 |
| | | DEVICE OVERVIEW | Device overview table extended and updated. Changed recommendation for VZ. | 14 |

| Rel. | Rel. Date ¹ | Chapter | Modification | Page |
|------|------------------------|--------------------------------|---|------|
| A3 | 2017-02-20 | DESCRIPTION | Added "General notice on materials under excessive conditions" | 2 |
| | | PACKAGING INFORMATION | Changed footnote for TM1, TM2, TMO | 3 |
| | | ABSOLUTE MAXIMUM RATINGS | G002, G004: Changed max. values | 5 |
| | | THERMAL DATA | T02: Permissible Storage Temperature Range added T04: Corrected unit | 5 |
| | | ELECTRICAL CHARACTERISTICS | 405/407: Max./Min. value changed 605/606: Added max. value | 6,7 |
| | | SIGNAL DEFINITIONS | Added definition of positive direction of movement for linear series | 9 |
| | | VOLTAGE DOMAINS | Added section | 10 |
| | | ANALOG / MIXED OPERATION MODES | Added note on VZ Changed figure | 11 |
| | | DIGITAL OPERATION MODES | Added note on VZ | 13 |
| | | INDEX DETECTION THRESHOLD | Added Note | 14 |
| | | POWER CONTROL | Description of power control added | 14 |
| | | DEVICE OVERVIEW | Changed Code Disc P/O Code, Type | 19 |

| Rel. | Rel. Date ¹ | Chapter | Modification | Page |
|------|------------------------|----------------------------|---|------|
| A4 | 2020-06-08 | PACKAGING INFORMATION | AOI criteria added | 3 |
| | | ELECTRICAL CHARACTERISTICS | Added figure for Vs()low and Vs()hi | 8 |
| | | DIGITAL OPERATION MODES | Description of minimal edge distance updated. | 13 |
| | | SAFETY ADVICE | Added section | 14 |
| | | HANDLING ADVICE | Added section | 14 |
| | | DEVICE OVERVIEW | Added Vout()mx | 15 |

| Rel. | Rel. Date ¹ | Chapter | Modification | Page |
|------|------------------------|--|----------------------|------|
| B1 | 2023-03-08 | ABSOLUTE MAXIMUM RATINGS | ESD description | 5 |
| | | THERMAL DATA | MSL changed | 5 |
| | | DESIGN REVIEW: Notes On Chip Functions | Chapter added | 16 |
| | | ORDERING INFORMATION | Detailed description | 20 |

| Rel. | Rel. Date ¹ | Chapter | Modification | Page |
|------|------------------------|-----------------------|----------------------|------|
| B2 | 2023-08-01 | PACKAGING INFORMATION | AOI CRITERIA updated | 3 |

¹ Release Date format: YYYY-MM-DD

iC-PR Series

REFLECTIVE OPTO ENCODERS



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ORDERING INFORMATION

| Type | Package | Options | Order Designation |
|----------------|--|-----------------------|----------------------|
| iC-PRnnnn | 24-pin optoQFN, 4 mm x 4 mm, 0.9 mm thickness RoHS compliant | nnnn = device version | iC-PRnnnn oQFN24-4x4 |
| Evaluation kit | iC-PR0464 oQFN24-4x4, PR1M (61mm x 64 mm), Code Disc PR06PS | | iC-PR0464 EVAL PR1M |
| | iC-PR1456 oQFN24-4x4, PR1M (61mm x 64 mm), Code Disc PR27PS+PR29PS | | iC-PR1456 EVAL PR1M |
| | iC-PR2604 oQFN24-4x4, PR1M (61mm x 64 mm), Code Disc PR24PS | | iC-PR2604 EVAL PR1M |
| | iC-PR2656 oQFN24-4x4, PR1M (61mm x 64 mm), Code Disc PR25PS+PR30PS | | iC-PR2656 EVAL PR1M |
| | iC-PR4307 oQFN24-4x4, PR1M (61mm x 64 mm), Code Disc PR28PS | | iC-PR4307 EVAL PR1M |
| | iC-PR256 oQFN24-4x4, PR1M (61mm x 64 mm), Linear Scale PR01FL | | iC-PR256 EVAL PR1M |
| Mother board | Adapter PCB PR2M (80 mm x 110 mm) | incl. ribbon cable | iC-PR EVAL PR2M |

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